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Lecture 6

①

- can never have perfect knowledge of a state
- errors can also occur in preparation, evolution, or measurement
- relax this assumption & "noisy quantum theory" subsumes probability theory & noiseless quantum theory

Proceed in the following order:

- 1) density operators
- 2) general form of measurements
- 3) composite noisy systems
- 4) noisy evolution

Noisy States

Suppose a third party prepares a state $|t_x\rangle$ w/ prob. $p(x)$, but doesn't tell us which one he prepared

- our best description is as ensemble

$$\mathcal{E} = \{p(x), |t_x\rangle\}$$

What is the outcome of a measurement w/ projectors $\{\Pi_j\}$ such that $\sum_j \Pi_j = I$?

Let J denote R.V. for measurement outcome

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Suppose that state is $|N_x\rangle$.

Then conditional probability for getting outcome j is

$$P_{j|x}(j|x) = \langle \psi_x | \Pi_j | \psi_x \rangle$$

+ post-measurement state is

$$\frac{\Pi_j | \psi_x \rangle}{\sqrt{P(j|x)}}$$

But, since we don't know x , the relevant prob. for measurement outcome is

unconditional prob. $P_j(j)$

From law of total prob.,

$$\begin{aligned} P_j(j) &= \sum_x P_{j|x}(j|x) P_x(x) \\ &= \sum_x \langle \psi_x | \Pi_j | \psi_x \rangle P_x(x) \end{aligned}$$

Define the trace of operator A as

$$\text{Tr}\{A\} = \sum_i \langle i | A | i \rangle \quad \text{where } \{ |i\rangle \} \text{ o.n. basis}$$

Then

$$\begin{aligned} \text{Tr}\{\Pi_j | \psi_x \rangle \langle \psi_x | \} &= \sum_i \langle i | \Pi_j | \psi_x \rangle \langle \psi_x | i \rangle \\ &= \sum_i \langle \psi_x | i \rangle \langle i | \Pi_j | \psi_x \rangle \\ &= \langle \psi_x | \left(\sum_i i \langle i | \right) \Pi_j | \psi_x \rangle \\ &= \langle \psi_x | \Pi_j | \psi_x \rangle \end{aligned}$$

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$$\begin{aligned} \text{Then } p_j(j) &= \sum_x \text{Tr} \{ \pi_j | \psi_x \rangle \langle \psi_x | \} p_x(x) \\ &= \text{Tr} \{ \pi_j \left(\sum_x p_x(x) | \psi_x \rangle \langle \psi_x | \right) \} \end{aligned}$$

rewrite as

$$p_j(j) = \text{Tr} \{ \pi_j \rho \}$$

where ρ is density operator

$$\rho \equiv \sum_x p_x(x) | \psi_x \rangle \langle \psi_x |$$

AKA expected density operator for ensemble

$$\rho = \mathbb{E}_x \{ | \psi_x \rangle \langle \psi_x | \}$$

Properties of density operator

1) unit trace, 2) positive 3) Hermitian

$$1) \text{ Tr} \{ \rho \} = \text{Tr} \left\{ \sum_x p(x) | \psi_x \rangle \langle \psi_x | \right\}$$

$$= \sum_x p(x) \text{Tr} \{ | \psi_x \rangle \langle \psi_x | \}$$

$$= \sum_x p(x) \langle \psi_x | \psi_x \rangle$$

$$= \sum_x p(x) = 1$$

$$2) \forall |\psi\rangle \quad \langle \psi | \rho | \psi \rangle \geq 0$$

$$\langle \psi | \rho | \psi \rangle = \langle \psi | \left(\sum_x p(x) | \psi_x \rangle \langle \psi_x | \right) | \psi \rangle$$

$$= \sum_x p(x) \langle \psi | \psi_x \rangle \langle \psi_x | \psi \rangle$$

$$= \sum_x p(x) | \langle \psi_x | \psi \rangle |^2 \geq 0$$

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$$\begin{aligned}
 3) \rho^+ &= \left(\sum_x p(x) |Y_x\rangle\langle Y_x| \right)^+ \\
 &= \sum_x p(x) (|Y_x\rangle\langle Y_x|)^+ \\
 &= \sum_x p(x) |Y_x\rangle\langle Y_x| \\
 &= \rho
 \end{aligned}$$

every ensemble has a unique density operator
but ~~not~~ every density operator does not
correspond to a unique ensemble

e.g. $\{\{\frac{1}{2}, |0\rangle\}, \{\frac{1}{2}, |1\rangle\}\}$

$$+ \{\{\frac{1}{2}, |+\rangle\}, \{\frac{1}{2}, |- \rangle\}\}$$

have same density operator

$$\frac{I}{2} \quad (\text{maximally mixed state})$$

In spite of this, there is a "canonical" ensemble
for a given density operator (though still not
unique)

since every density operator ρ is
Hermitian, can diagonalize it

$$\rho = \sum_{x=0}^{d-1} r_x |\phi_x\rangle\langle\phi_x|$$

r \uparrow
 eigenvalues o.n.
 eigenvectors
 (probabilities)

ensemble is then

$$\sum r_x |\phi_x\rangle\langle\phi_x|$$

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can say that the density operator is "the state" b/c we can calculate probabilities w/ it.

consider pure qubit state

$$|\psi\rangle \equiv \cos\left(\frac{\theta}{2}\right)|0\rangle + e^{i\varphi} \sin\left(\frac{\theta}{2}\right)|1\rangle$$

density operator is

$$\begin{aligned}
 |\psi\rangle\langle\psi| &= \left(\cos\left(\frac{\theta}{2}\right)|0\rangle + e^{i\varphi} \sin\left(\frac{\theta}{2}\right)|1\rangle \right) \\
 &\quad \left(\cos\left(\frac{\theta}{2}\right)\langle 0| + e^{-i\varphi} \sin\left(\frac{\theta}{2}\right)\langle 1| \right) \\
 &= \cos^2\left(\frac{\theta}{2}\right)|0\rangle\langle 0| + e^{i\varphi} \sin\left(\frac{\theta}{2}\right)\cos\left(\frac{\theta}{2}\right)|1\rangle\langle 0| \\
 &\quad + e^{-i\varphi} \cos\left(\frac{\theta}{2}\right)|0\rangle\langle 1| + \sin^2\left(\frac{\theta}{2}\right)|1\rangle\langle 1|
 \end{aligned}$$

put in matrix "density matrix"

$$\begin{pmatrix} \cos^2\left(\frac{\theta}{2}\right) & e^{-i\varphi} \sin\left(\frac{\theta}{2}\right) \cos\left(\frac{\theta}{2}\right) \\ e^{i\varphi} \sin\left(\frac{\theta}{2}\right) \cos\left(\frac{\theta}{2}\right) & \sin^2\left(\frac{\theta}{2}\right) \end{pmatrix}$$

Trig identities gives

$$\begin{aligned}
 \frac{1}{2} & \begin{Bmatrix} 1+\cos\theta & \sin\theta(\cos\varphi-i\sin\varphi) \\ \sin\theta(\cos\varphi+i\sin\varphi) & 1-\cos\theta \end{Bmatrix} \\
 = \frac{1}{2} & \begin{Bmatrix} 1+r_x & r_x-i r_y \\ r_x+i r_y & 1-r_x \end{Bmatrix}
 \end{aligned}$$

$$r_x = \sin\theta \cos\varphi$$

$$r_y = \sin\theta \sin\varphi$$

$$r_z = \cos\theta$$

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can use Pauli matrices I, X, Y, Z
to write as

$$\frac{1}{2} (I + r_x X + r_y Y + r_z Z)$$

$$\vec{r} = (r_x, r_y, r_z) \text{ - Bloch vector}$$

can write any pure state like this

Also, $\sum_i p(i) |t_i\rangle \langle t_i| \Rightarrow \vec{r} = \sum_i p(i) \vec{r}_i$

gets points inside the Bloch sphere (not just on
the boundary)

Very useful when reasoning about qubits

Ensemble of Ensembles

$$\mathcal{F} = \{p(x), \rho_x\}$$

ensemble of density operators

"two layers of randomization"

1) $p(x)$

2) could say that each density operator

ρ_x arises from ensemble $\{p_{y|x}(y|x), |t_{x,y}\rangle\}$
so that

$$\rho_x = \sum_y p_{y|x} |t_{x,y}\rangle \langle t_{x,y}|$$

$$= \sum_y p(y|x) |t_{x,y}\rangle \langle t_{x,y}|$$

density operator for someone who is ignorant of
 x is

$$\rho = \sum_{x,y} p(y|x) p(x) |t_{x,y}\rangle \langle t_{x,y}| = \sum_x p(x) \rho_x$$

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Noiseless Evolution of an ensemble

Suppose some ensemble $\{p(x), |4_x\rangle\}$
suppose we know the state $|4_x\rangle$

Then after evolution U , new state is

$$U|4_x\rangle$$

can say that we have a new ensemble

$$\{p(x), U|4_x\rangle\}$$

~~density operator~~ for original ensemble is

$$\rho = \sum_x p(x) |4_x\rangle \langle 4_x|$$

density operator for evolved ensemble is

$$\sum_x p(x) U|4_x\rangle \langle 4_x|U^\dagger = U \left(\sum_x p(x) |4_x\rangle \langle 4_x| \right) U^\dagger$$

$$= \boxed{U \rho U^\dagger}$$

↑
evolution of the density operator

Noiseless Measurement

have ensemble $\{p(x), |4_x\rangle\}$ again
Suppose for now that we know the state is $|4_x\rangle$
if we perform a measurement $\{\Pi_j\}$

probability for getting j is

$$P_{J|x}(j|x) = \langle 4_x | \Pi_j | 4_x \rangle \quad \text{post measurement state is}$$

$$\frac{\Pi_j |4_x\rangle}{\sqrt{P_{J|x}(j|x)}}$$

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Suppose that we perform measurement,
but we don't know on which state
we performed the measurement
(though we know measurement result)
ensemble is then

$$\mathcal{E}_j \equiv \left\{ \underbrace{p_{x|j}(x|j)}_{\text{we know}}, \underbrace{\frac{\pi_j | \psi_x \rangle \langle \psi_x | \pi_j}{\sqrt{p_{j|x}(j|x)}}}_{\sqrt{p_{j|x}(j|x)}} \right\}$$

density operator of ensemble is

$$\begin{aligned} & \sum_x p(x) \frac{\pi_j | \psi_x \rangle \langle \psi_x | \pi_j}{p_{j|x}(j|x)} \\ &= \pi_j \left(\sum_x \frac{p(x|j)}{p(j|x)} | \psi_x \rangle \langle \psi_x | \right) \pi_j \quad (\text{Note: } p(x|j) \\ &\quad = \frac{p(j|x)}{p(j)}) \\ \therefore &= \pi_j \left(\sum_x \frac{p(j|x)p(x)}{p(j|x)p(j)} | \psi_x \rangle \langle \psi_x | \right) \pi_j \\ &= \pi_j \left(\sum_x p(x) | \psi_x \rangle \langle \psi_x | \right) \pi_j \\ &= \boxed{\frac{\pi_j \rho \pi_j}{p(j)}} \end{aligned}$$

← This is how the density operator evolves under measurement

use law of total probability to get $p(j)$

$$\begin{aligned} p_j(j) &= \sum_x p_{j|x}(j|x) p(x) \\ &= \sum_x \langle \psi_x | \pi_j | \psi_x \rangle p(x) \\ &= \sum_x \text{Tr} \{ | \psi_x \rangle \langle \psi_x | \pi_j \} p(x) \\ &= \text{Tr} \{ \left(\sum_x p(x) | \psi_x \rangle \langle \psi_x | \right) \pi_j \} \\ &= \text{Tr} \{ \rho \pi_j \} \end{aligned}$$

measures the "shadow"
of ρ on π_j subspace

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1/20/2011 Probability Theory as a special case of the noisy quantum theory

pick ensemble $\{p(x), |x\rangle\}$

of classical states, measuring $|x\rangle$ are O.N. & thus distinguishable
(can distinguish them w/
a measurement w/ projection
operators $\{|x\rangle\langle x|\}$)

analogy of prob. distribution is density operator:

$$p_x(x) \leftrightarrow \rho$$

Analogy of R.V., X is observable

$$X \leftrightarrow X = \sum_x x|x\rangle\langle x|$$

$$\mathbb{E}\{X\} = \text{Tr}\{X\rho\}$$

Why?

$$\text{Tr}\{X\rho\} = \text{Tr}\left\{\sum_x x|x\rangle\langle x| \sum_{x'} p(x')|x'\rangle\langle x'|\right\}$$

$$= \sum_{x,x'} x p(x') \langle x|x'\rangle \langle x'|x\rangle$$

$$= \sum_{x,x'} x p(x') \delta_{xx'}$$

$$= \sum_x x p(x)$$

↑ same formula as classical expectation

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Indicator r.v.

$$I_A(x) = \begin{cases} 1 & : x \in A \\ 0 & : x \notin A \end{cases}$$

$$\mathbb{E}\{I_A(x)\} = \sum_{x \in A} p_x(x) \equiv p_x(A)$$

can form an indicator observable

$$I_A(x) = \sum_{x \in A} |x\rangle\langle x|$$

same calculation shows that

$$\text{Tr}\{I_A(x)\rho\} = p_x(A)$$

since indicator observable is a projector
we can make a measurement out of it:

~~$$\{I_A(x), I_{A^c}(x)\}$$~~

$$\text{where } I_{A^c}(x) = I - I_A(x)$$

$$= \sum_{x \in A^c} |x\rangle\langle x|$$

result of such a measurement is to
project onto subspace $I_A(x)$ w/
prob. $p_x(A)$ + onto subspace $I_{A^c}(x)$
w prob. $p_x(A^c)$

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Further connections:

two disjoint sets $A + B$

probability of union is

$$p(A \cup B) = p(A) + p(B)$$

can do similar calculation in QM

$$\Pi_A = \sum_{x \in A} |x\rangle\langle x|$$

$$\Pi_B = \sum_{x \in B} |x\rangle\langle x|$$

$$\Pi_{A \cup B} = \sum_{x \in A \cup B} |x\rangle\langle x| = \Pi_A + \Pi_B$$

can show that

$$\text{Tr}\{\Pi_{A \cup B}\} = p(A) + p(B)$$

Intersection of sets:

$$p(A \cap B)$$

can multiply these projectors to get
intersection projector

$$\Pi_A \Pi_B = \sum_{x \in A} |x\rangle\langle x| \sum_{x' \in B} |x'\rangle\langle x'|$$

$$= \sum_{x \in A, x' \in B} |x\rangle\langle x'| \langle x|x'\rangle$$

$$= \sum_{x \in A, x' \in B} |x\rangle\langle x'| \delta_{x, x'}$$

$$= \sum_{x \in A \cap B} |x\rangle\langle x|$$

$$= \Pi_{A \cap B}$$

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1/20/2011 intuition helpful,

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but it all breaks down w/ a little
non-orthogonality!

(play w/ $|10\rangle + |11\rangle$, for example)

projectors not the most general form
of measurement

- in general, can be set of operators
 $\{M_j\}$ such that

$$\sum_j M_j + M_j^\dagger = I$$

for pure states, probabilities from
measurement are

$$p(j) = \langle + | M_j + M_j^\dagger | + \rangle$$

+ post-measurement state is

$$\frac{M_j |+\rangle}{\sqrt{p(j)}}$$

for mixed states,

$$p(j) = \text{tr} \{ M_j + M_j^\dagger \rho \}$$

+ post-measurement state is

$$\frac{M_j \rho M_j^\dagger}{p(j)}$$

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POVM Formalism

useful if we are just interested
in classical outcome of measurement,
not post-measurement state

(application in classical communication
over a quantum channel)

POVM - (positive operator-valued measure)
some operators $\sum_j \lambda_j$
 λ_j POVM elements

$$\forall j \quad \lambda_j \geq 0$$

$$\sum_j \lambda_j = I$$

("just like" probabilities)

If state is ρ , probability for
getting outcome j is

$$\text{Tr} \{ \lambda_j \rho \}$$