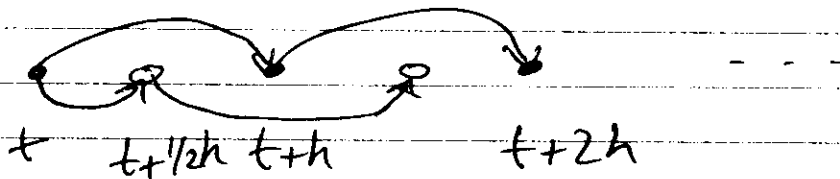


# Lecture 18

①

Recall leap-frog method



Equations were

$$x(t+h) = x(t) + h f(x(t+\frac{1}{2}h), t+\frac{1}{2}h)$$

$$x(t+\frac{3}{2}h) = x(t+\frac{1}{2}h) + h f(x(t+h), t+h)$$

The method is time reversal  
symmetric

Substitute  $h \rightarrow -h$  & get

$$x(t-h) = x(t) - h f(x(t-\frac{1}{2}h), t-\frac{1}{2}h)$$

$$x(t-\frac{3}{2}h) = x(t-\frac{1}{2}h) - h f(x(t-h), t-h)$$

Now time shift  $t \rightarrow t + \frac{3}{2}h$   
& get

②

$$x(t+1/2h) = x(t+3/2h) - h f(x(t+h), t+h)$$

$$x(t) = x(t+h) - h f(x(t+1/2h), t+1/2h)$$

Compare to (\*) & we see that  
the equations are the same,  
but run backwards

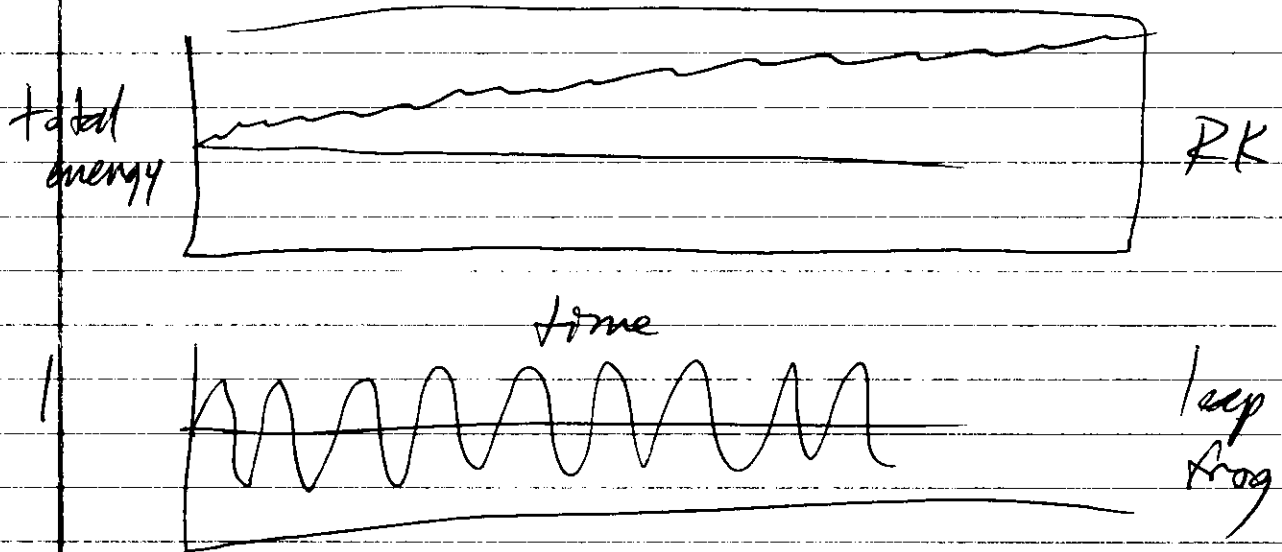
This is not true of Runge-Kutta  
(can do the same calculation &  
you won't have the time  
reversal symmetry)

Why is the time reversal symmetry  
important? One reason is  
conservation of energy.

When using Runge-Kutta for  
nonlinear pendulum, the total  
energy fluctuates & drifts over time

(3)

For the leap-frog method,  
the total energy fluctuates but  
there is no drift



So leap frog method is useful  
for solving energy conserving  
physical systems over long periods  
of time.

## Verlet method

(4)

variation of leap frog

Suppose equations of motion take

the form 
$$\frac{d^2x}{dt^2} = f(x, t)$$

e.g. ,  $F = ma$

can convert to

$$\frac{dx}{dt} = v \quad \frac{dv}{dt} = f(x, t)$$

could directly apply leap frog method to vector  $\underline{r} = (x, v)$

$$w/ \quad \frac{d\underline{r}}{dt} = \underline{f}(\underline{r}, t)$$

But let's instead write out

the leap frog method in full

$$x(t+h) = x(t) + h v(t+\frac{1}{2}h) \quad (\text{1st eq.})$$

$$v(t+\frac{3}{2}h) = v(t+\frac{1}{2}h) + h f(x(t+h), t+h)$$

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We can derive a full solution using these ~~two~~ equations alone. The vector method requires double the work, but here we only calculate  $x$  @  $t+kh$  &  $v$  @  $t+(k+1/2)h$

- works for diff eq's w/ special

$$\begin{array}{ccc} \text{form} & \frac{dx}{dt} = v & \frac{dv}{dt} = f(x,t) \\ & \uparrow & \uparrow \\ & \text{doesn't} & \text{doesn't} \\ & \text{depend on} & \text{depend} \\ & x & \text{on } v \end{array}$$

- Potential issue: What if we want to calculate quantity that depends on  $x$  &  $v$ , like total energy? we only have  $x$  @  $t+kh$  &  $v$  @  $t+(k+1/2)h$

(6)

Supposing that we did know

$v(t+h)$  then we could calculate ~~it~~

~~it~~  $v(t+1/2h)$  by going

backwards w/ the Euler method

giving

$$v(t+1/2h) = v(t+h) - 1/2 h f(x(t+h), t+h)$$

then rearrange as

$$v(t+h) = v(t+1/2h) + 1/2 h f(x(t+h), t+h)$$

So the full Verlet method is

$$x(t+h) = x(t) + h v(t+1/2h)$$

$$k = h f(x(t+h), t+h)$$

$$v(t+h) = v(t+1/2h) + 1/2 k$$

$$v(t+3/2h) = v(t+1/2h) + k$$

put "bars" underneath to get vector quantities ...

(7)

## Modified midpoint method

Another advantage of leap frog method is that the total error is an even function of the step size  $h$  (due to time reversal symmetry)

⇒ expansion of error in power series of  $h$  has only even terms & no odd terms.

We can see this in more detail:

A single step of leap frog method is accurate to order  $h^2$  & has error to order  $h^3$

Write error as  $\epsilon(h)$  w/

first term proportional to  $h^3$ .

What do the other terms look like?

(8)

Take a small <sup>forward</sup> step w/ leap frog method.

Gives the solution plus  $\epsilon(h)$   
(error)

Now go backwards, i.e., step size is  $-h$

Due to time symmetry,

the change in the solution is

the reverse of the forward change

$\Rightarrow$  backward error is the negative of the forward error, i.e.,

$$\epsilon(-h) = -\epsilon(h)$$

$\Rightarrow \epsilon(h)$  is an odd function & has <sup>only</sup> odd powers in Taylor expansion.

For overall error, we compute error on a single step times the # of steps.



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So if the time interval of interest is  $\Delta$ , then # of steps is  $\Delta/h \Rightarrow$

total error is  $\epsilon(h) = \frac{\Delta}{h}$

i.e., an even function of error.

w/ first term proportional to  $h^2$ .

Slight catch: For the 1st step of

leap frog, we take a  $1/2$  step using Euler method & introduce an error of order  $h^2$  (as is case w/ Euler method).

However, Euler method higher order terms are not even.

So the total error has even & odd powers.

(10)

Can solve this problem using  
the modified midpoint method.

Suppose we want to solve starting

@  $t$  & ending @  $t+H$  where  
 $H$  is not  
small.

use  $n$  steps of size  $h = H/n$

can write leap frog as

$$x_0 = x(t)$$

$$y_1 = x_0 + \frac{1}{2}h f(x_0, t)$$

& then

$$x_1 = x_0 + h f(y_1, t + \frac{1}{2}h)$$

$$y_2 = y_1 + h f(x_1, t + h)$$

$$x_2 = x_1 + h f(y_2, t + \frac{3}{2}h)$$

etc.

general form is

$$y_{m+1} = y_m + h f(x_m, t + mh)$$

$$x_{m+1} = x_m + h f(y_{m+1}, t + (m + \frac{1}{2})h)$$

(11)

last 2 points are

$$y_n = x(t + H - 1/2h)$$

$$x_n = x(t + H)$$

usually would take  $x_n$  as

solution but we can also estimate  $x(t + H)$  using Euler method as

$$x(t + H) = y_n + 1/2h f(x_n, t + H)$$

can take the average of the

two estimates for  $x(t + H)$  to be the estimate:

$$x(t + H) = \frac{1}{2} \left[ x_n + y_n + \frac{1}{2} h f(x_n, t + H) \right]$$

can show that doing so

cancels out the  $o(h)$  order error terms introduced in the

1st step of Euler method

(need to track errors carefully to see this)

contains only even-order error terms. Remember how this was useful for Romberg integration? This will be useful for a similar method for solving diff. eq's

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### Bulirsch - Stoer Method

reminiscent of Romberg integration

Suppose we wish to solve

$$\frac{dx}{dt} = f(x, t)$$

from  $t$  to  $t + H$

Begin by using a single step of size  $H$  & use modified midpoint method

Let  $h_1 = H$

gives an estimate of  $x(t+H)$ ,

call it  $R_{1,1}$ .

Now go back to time  $t$ ,

divide interval into 2 steps of

size  $h_2 = \frac{1}{2}H$ . Gives

another estimate of  $x(t+H)$ ,

call it  $R_{2,1}$ .

Since total error of modified midpoint method is an even function of step size, we have that

$$x(t+H) = R_{2,1} + c_1 h_2^2 + o(h_2^4)$$

where  $c_1$  is some constant

(14)

Also consider that

$$\begin{aligned}x(t+H) &= R_{1,1} + c_1 h_1^2 + o(h_1^4) \\ &= R_{1,1} + 4c_1 h_2^2 + o(h_2^4)\end{aligned}$$

using  $h_1 = 2h_2$

Then since both of those are equal  
to  $x(t+H)$ , equate them  
~~to get~~ to  
get

$$c_1 h_2^2 = \frac{1}{3} (R_{2,1} - R_{1,1}) + o(h_2^4)$$

Substitute into the above to get

$$\begin{aligned}x(t+H) &= R_{2,1} + \frac{1}{3} (R_{2,1} - R_{1,1}) \\ &\quad + o(h_2^4)\end{aligned}$$

- method has ~~error~~ error of order  $h_2^4$

- call the new estimate

$$R_{2,2} = R_{2,1} + \frac{1}{3} (R_{2,1} - R_{1,1})$$

can continue w/ this idea

- increase # of steps to 3

$$\text{so that } h_3 = \frac{H}{3}$$

- solve from  $t$  to  $t+H$  to get estimate  $R_{3,1}$

calculate estimate

$$R_{3,2} = R_{3,1} + \frac{4}{5} (R_{3,1} - R_{2,1})$$

(reasoning same as before)

we can then write

$$x(t+H) = R_{3,2} + c_2 h_3^4 + O(h_3^6)$$

w/  $c_2$  a constant

From before we have that

$$\begin{aligned} x(t+H) &= R_{2,2} + c_2 h_2^4 + O(h_2^6) \\ &= R_{2,2} + \frac{81}{16} c_2 h_3^4 + O(h_2^6) \end{aligned}$$

$$\text{using } h_2 = \frac{3}{2} h_3$$

(16)

Equating & rearranging gives

$$C_2 h_3^4 = \frac{16}{65} (R_{3,2} - R_{2,2})$$

substituting back in gives

$$x(t+H) = R_{3,3} + O(h_3^6)$$

$$\text{where } R_{3,3} = R_{3,2} + \frac{16}{65} (R_{3,2} - R_{2,2})$$

result is accurate to order  $h_3^6$

w/ just 3 steps.

Power is the cancellation of higher order errors on successive steps

done w/ <sup>modified</sup> midpoint method having only even-order terms.

can continue this process iteratively  
& estimate is

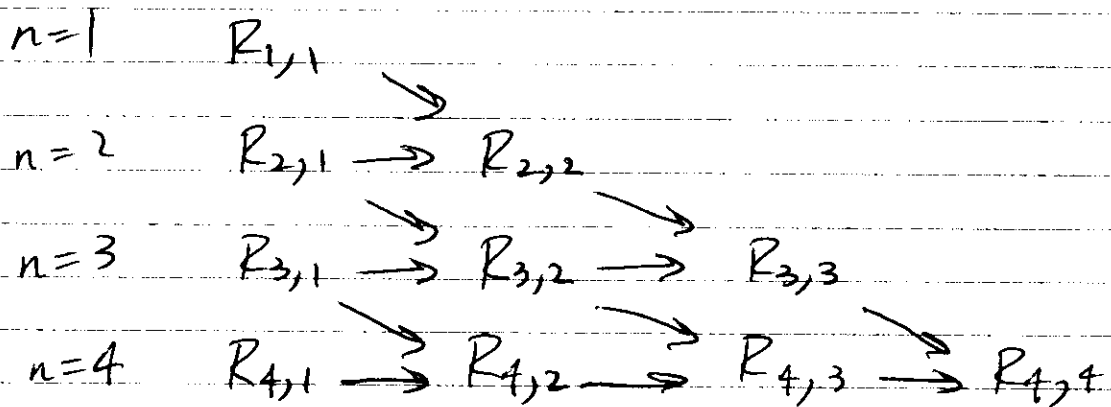
$$x(t+H) = R_{n,m+1} + O(h_n^{2m+2})$$



w/  $m < n$  +

$$R_{n,m+1} = R_{n,m} + \frac{R_{n,m} - R_{n-1,m}}{[n/(n-1)]^{2m} - 1}$$

diagram similar to that for Romberg integration



modified  
midpoint  
method

Richardson extrapolation

also get estimate of error as

$$\frac{R_{n,m} - R_{n-1,m}}{[n/(n-1)]^{2m} - 1}$$

limitations :

- 1) answer only accurate for  $x(t+H)$
- 2) method only converges quickly if the power series expansion of  $x(t+H)$  converges quickly.

can overcome these problems by dividing interval into smaller ones

↳ apply ~~Burton~~ - Stoer & Burlirsch

each one.